Numerical Modelling for Analysis of High Enthalpy Impulse Facilities

ISSW35: Shock Waves Down Under, Brisbane 2025

Dr. Nick Gibbons and A/Prof. Rowan Gollan

Centre for Hypersonics, The University of Queensland Saturday, 5th July

About Us!

Rowan Gollan:

- PhD in hypersonic flow modelling, 2009
- lecturer in School of Mechanicl & Mining Engineering
- researcher at Centre for Hypersonics
- member of core development team for Eilmer



Nick Gibbons:

- PhD in supersonic combustion, 2019
- Started as postdoctoral fellow @ UQ in 2020
- CFD code dev (Eilmer) and HPC sims expert





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nicholas-gibbons-67342555

This Session

This session is about numerical modelling of Impulse Facilities:

- Why?
- How?
 - ► An overview of approaches and (local) tools
 - Scenario: modelling the T4 reflected shock tunnel
 - ESTCn
 - NENZ1d
 - Eilmer
 - ► Introduction to L1d
 - Introduction to Eilmer
 - ► Scenario: simulation of a T4 experiment

Modelling and simulation of impulse facilities can address questions on design and operation.

What is the flow condition coming out of my facility? \rightarrow estimation of test conditions

What's going wrong with my facility? \rightarrow diagnosis of behaviour

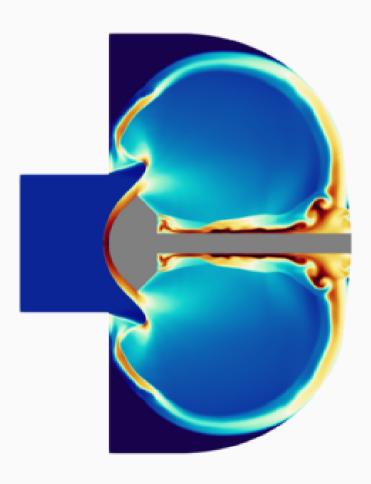
How useful or useable is my test gas? \rightarrow ditto

What if I replaced gas A with B? What if I operated \rightarrow what-if? exploratory questions

in a different mode?

I want to design a new facility \rightarrow design and optimisation

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 \rightarrow estimation of test conditions

What's going wrong with my facility?

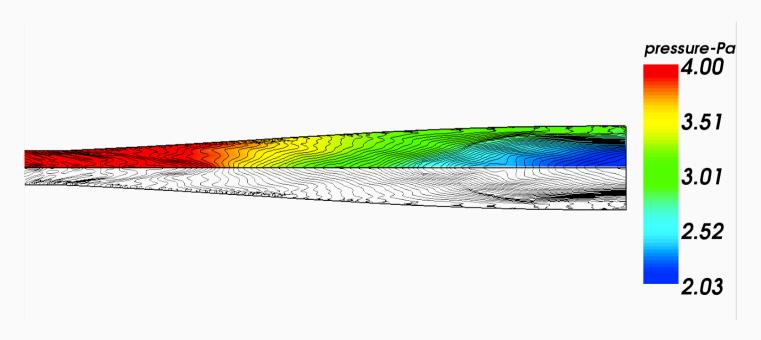
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- \rightarrow ditto
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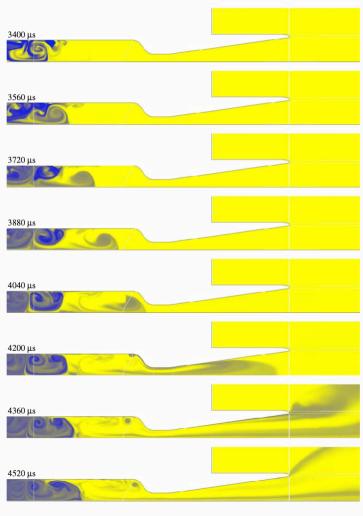
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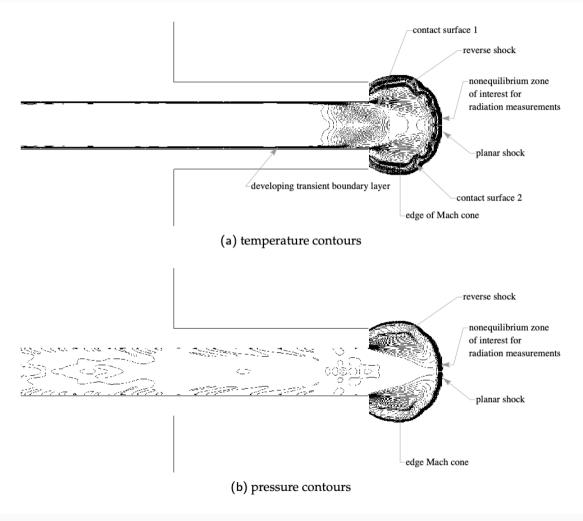
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Why model an impulse facility? Estimating test gas contamination



source: Goozée et al. (2006) Shock Waves, 15(3) [1]

Why model an impulse facility? Estimating test gas structure



source: Gollan (2008), PhD thesis [2]

What is the flow condition coming out of my facility? \rightarrow estimation of test conditions

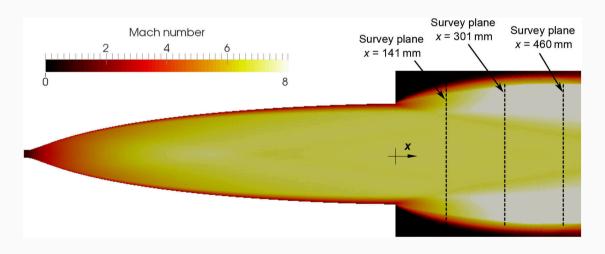
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How can we analyse impulse facilities? a categorisation of modelling approaches

Physical fidelity

- state-to-state estimates built from simple/ idealised flow processes
- space-time discretisations of the governing equations

Geometry representation

- abstracted: lengths, area ratios
- quasi-one-dimensional
- two dimensionsal: planar and *axisymmetric*
- three dimensional

Time to answer

- fractions of sections on a desktop
- 1000s of CPU hours on a parallel-processing high-performance computer

Information inputs

- inputs on nominal information
- inputs on measured information (*a priori*)
- data fusion approaches (a posteriori)

Applicability

- specialist tool
- general-purpose tool

How can we analyse impulse facilities? Overview of our toolkit

The Gasdynamics Toolkit (GDTk) is a collection of software tools for analysing hypersonic flow

- Developed over 30 years here in Australia, at UQ and UniSQ
- · Open-source and built with transparency and reproducibility in mind

	GDTk tools for analysing impulse facilities
ESTCN	RST shot processing. State-to-state eq chemistry.
NENZF1d	RST shot processing. Q1D nozzle calc with full nonequilibrium
PITOT3	XT and RST full facility calc with eq chemistry.
L1d	1D Lagrangian full facility sim with noneq and viscous losses
Eilmer	2D/3D CFD with full nonequilibrium and boundary layers

Project Website: [4]



ESTCn and Friends

Lots of activity in Australia over the years modelling Reflected Shock Tunnels

- 1960's: ESTC, NENZF (McIntosh @ ANU and Lordi et al. @ Cornell)
- 1990's: STN (P. Jacobs and Krek @ UQ)
- 2010's: ESTCj, NENZFr (P. Jacobs and many others @ UQ)
- Current: ESTCN, NENZF1d, Eilmer

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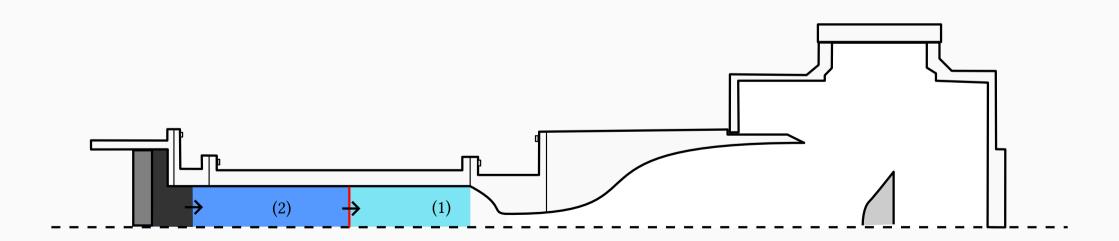
"Equilibrium Shock Tube Code" is really an *approach* that keeps getting reimplemented:

- There's an up to date version in the GDTk called ESTCN
- Let's look at how it works

State to State Modelling of Reflected Shock Tunnels

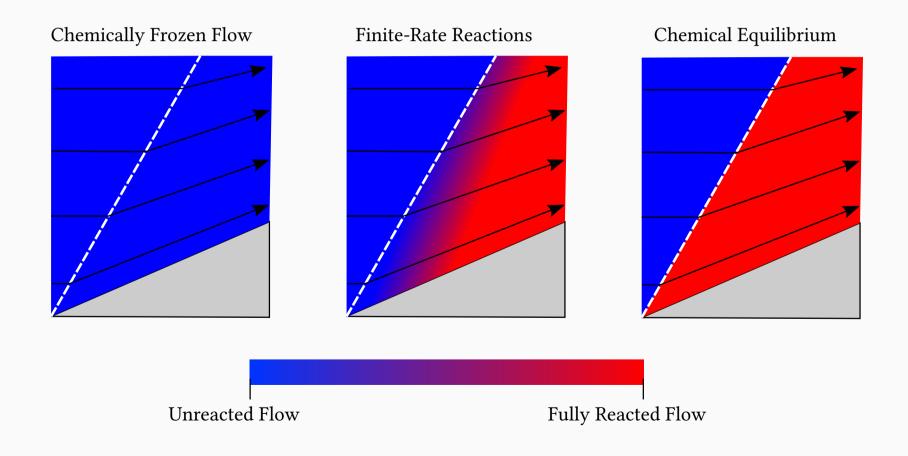
The Important Stuff begins with an incident shock in the shock tube:

- Experimentalists measure the incident shock speed
- Initial fill condition of state 1 is known
- Equilibrium shock jump relations solved to get state (2)



Impulse facility shocks are often quite strong:

• Flow chemistry occurs behind the shock, affecting its properties



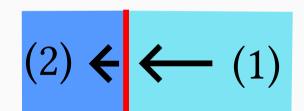
The Rankine-Hugoniot relations are still valid, but they need coupling to chemistry:

- Conservation of mass, momentum and energy and the shock:
- Remember that these are in the shock centered reference frame!

$$\rho_2 V_2 = \rho_1 V_1$$

$$\rho_2 V_2^2 + p_2 = \rho_1 V_1^2 + p_1$$

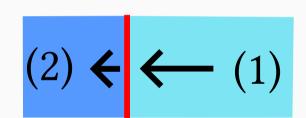
$$h_2 + \frac{1}{2} V_2^2 = h_1 + \frac{1}{2} V_1^2$$



The Rankine-Hugoniot relations are still valid, but they need coupling to chemistry:

• Solve iteratively by first guessing V_2 the postshock speed

$$\begin{split} \rho_2 &= \frac{\rho_1 V_1}{V_2} \\ p_2 &= \left(\rho_1 V_1^2 + p_1\right) - \rho_2 V_2^2 \\ e_2 &= \frac{\left(h_1 + \frac{1}{2} V_1^2\right) - \frac{1}{2} \rho_2 V_2^3 - p_2 V_2}{\rho_1 v_1} \end{split}$$



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- Rankine-Hugoniot equations give a speculative $\rho_2,\,p_2,\,{\rm and}\,\,e_2$
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- equilibrium-c, written by me! [5]
- My talk at the ISSW35 is all about it: (Monday at 1040am, Hawken 50-C207)

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Use internal energy e_2 and density ρ_2 to evaluate the equilibrium mole fractions:

$$X_2^s(\rho_2,e_2) = \left[X^{N_2}, X^{O_2}, X^N, \ldots \right]$$

The Rankine-Hugoniot relations are still valid, but they need coupling to chemistry:

- Solve iteratively by first guessing V_2 the postshock speed
- Rankine-Hugoniot equations give a speculative $\rho_2,\,p_2,\,{\rm and}\,\,e_2$
- Consult equilibrium chemistry solver for $X_2^s(\rho_2,e_2)$

Now we calculate *another* pressure:

$$p_{\rm eos} = \rho_2 \sum_s \frac{R_u}{M_s X_2^s} T_2$$

The Rankine-Hugoniot relations are still valid, but they need coupling to chemistry:

- Solve iteratively by first guessing V_2 the postshock speed
- RH equations give a speculative $\rho_2,\,p_2,\,{\rm and}\,\,e_2$
- Consult equilibrium chemistry solver for $X_2^s(\rho_2,e_2)$
- Equation of state gives a second pressure p_{eos}

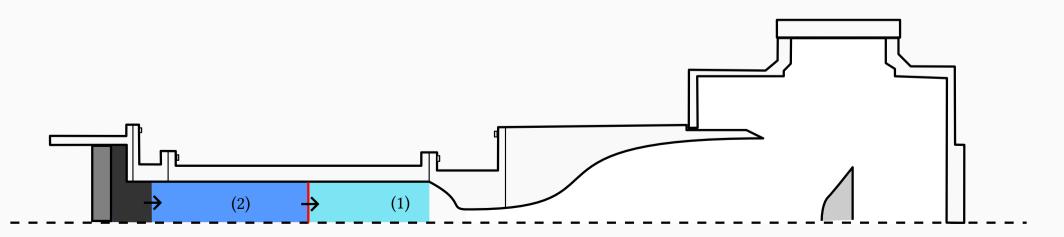
Iteratively adjust the guess V_2 until p_2 and p_{eos} are the same:

$$\frac{p_2-p_{\rm eos}}{p_2}\to 0$$

Step 1: Incident Shock Calculation

Example, T4 shot number 11760:

- Shock tube filled 194 kPa at T=300 K, shock speed measured at 2241 m/s
- Enthalpy: 4.6 MJ/kg, Flight Mach Number: ≈ 9.7 , Flight Alt $\approx 33~\mathrm{km}$

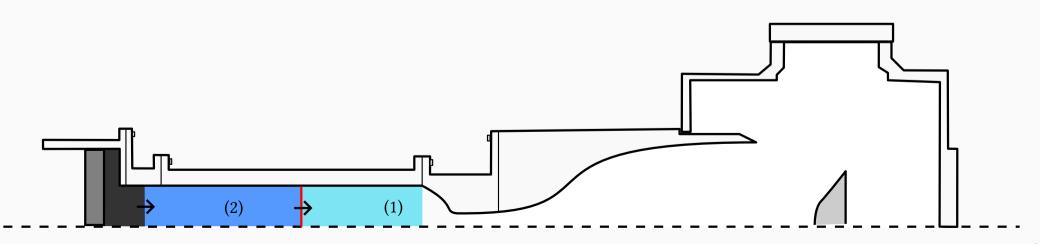


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State 2:	p (kPa)	T (K)	v (m/s)	NOX %	O %
Equilibrium	9701	2337	349.3	1.73	0.15
Ideal Gas	9359	2695	417.4	0.0	0.0
error	3.5%	15.0%	19.5%	100%	100%

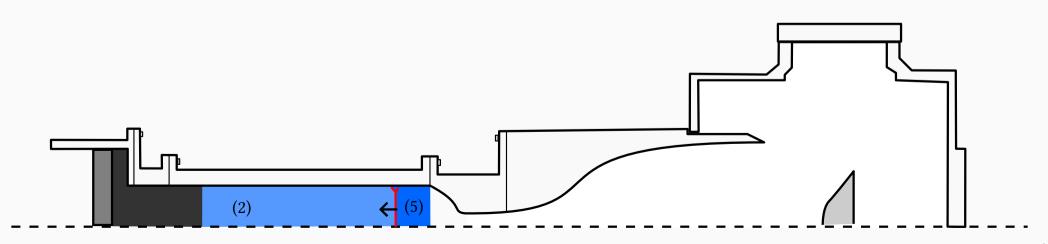


Step 2: Shock Reflection

This bit is a little more complicated

• Similar algorithm to the incident shock, but with fixed $V_2=0$ in the lab frame

	p (kPa)	T (K)	v (m/s)	NOX %	O %
State 1	194	300	0	0	0
State 2	9712	2338	349	1.75	0.15
State 5	76,469	4126	0	10.8	1.4



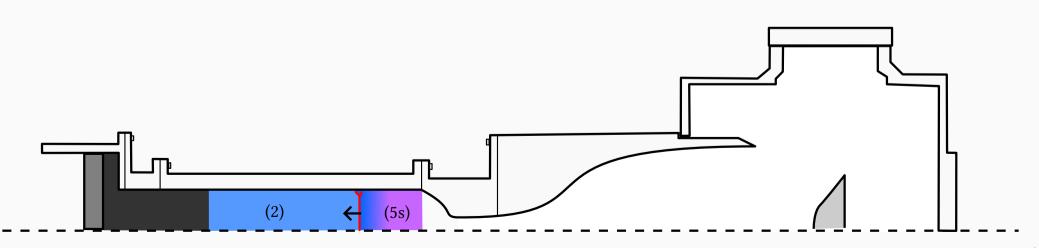
Step 3: Correct Stagnation Pressure

T4 and other Shock Tunnels have pressure sensors in the stagnation region

- We need to correct the perfectly stagnated state 5 using an isentropic expansion
- Most equilibrium solvers have a known pressure and entropy mode
- The cause of this discrepancy is debated (Any ideas from people in the room?)

Known:
$$p_{5s} = p_e$$
 $s_{5s} = s_5$

Compute:
$$T_{5s}(p_{5s}, s_5)$$
 $X_{5s}(p_{5s}, s_5)$

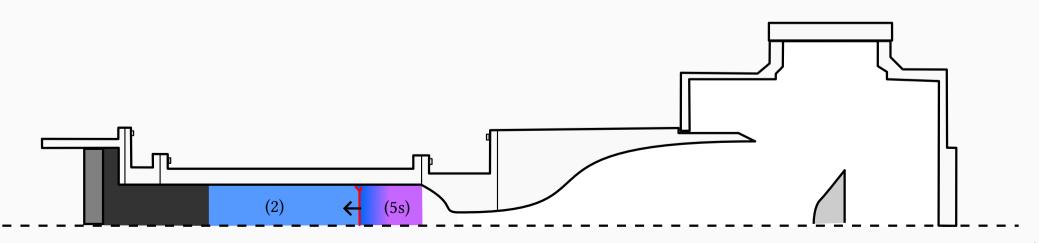


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State 5s	45,000	3768	0	8.9	0.9	



Step 4: Isentropic Expansion to Mach 1

From here we need to compute the nozzle, starting with the converging section

- Once again we use ps mode of our equilibrium solver
- Guess p_6 and iterate until $M_6=1$

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$$X_6^s = \operatorname{eqsolve}(p_6, s_{5s}) \qquad T_6 = \operatorname{eqsolve}(p_6, s_{5s})$$

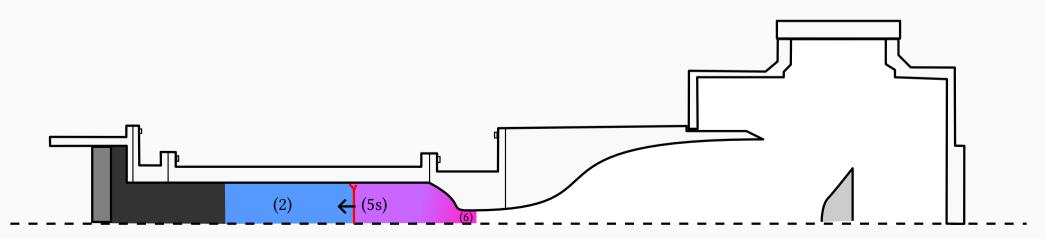
$$M_6 = \sqrt{\frac{2h_{5s} + V_{5s}^2 - 2h(X_6, T_6)}{\gamma(X_6)R(X_6)T_6}}$$

$$M_6(p_6) - 1 = 0$$

Step 5: Isentropic Expansion to Mach 1

From here we need to compute the nozzle, starting with the converging section:

	p (kPa)	T (K)	v(m/s)	NOX %	O %
State 1	194	300	0	0	0
State 2	9712	2338	349	1.75	0.15
State 5	76,469	4126	0	10.8	1.4
State 5s	45,000	3768	0	8.9	0.9
State 6	24,531	3391	1122	6.8	0.7

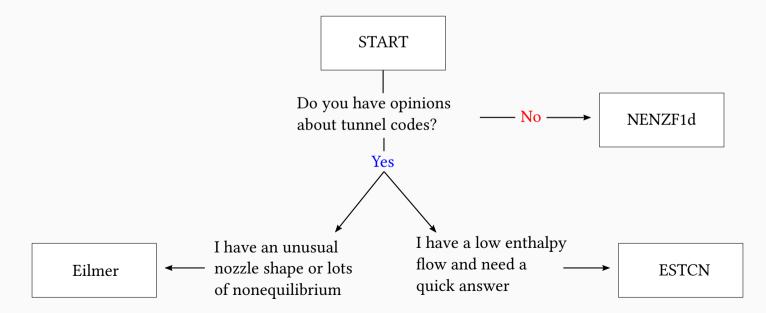


Step 6: Supersonic Expansion

This is where the calculation starts to get interesting:

- Expanding supersonic flows can have chemical and thermal nonequilibrium
- Viscous boundary layers and turbulence on the nozzle wall
- Some nozzle shapes can induce significant non-uniformity

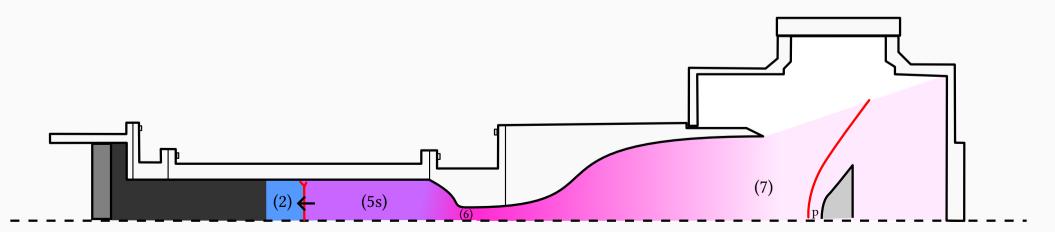
We have several different tools, with different levels of fidelity and run time:



Step 6: Isentropic Expansion with Known Pitot/Stag Ratio

If we have an actual pitot probe we can extend our current approach:

• Calculate the pitot/stag ratio and expand the flow until we reach it



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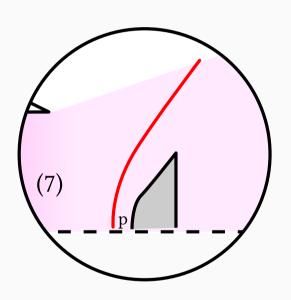
- Calculate the pitot/stag ratio and expand the flow until we reach it
- Once again we guess at p_7 and iterate

$$X_7^s = \text{eqsolve}(p_7, s_6)$$
 $T_7 = \text{eqsolve}(p_7, s_6)$

$$M_7 = \sqrt{\frac{2h_{5s} + V_{5s}^2 - 2h(X_7, T_7)}{\gamma(X_7)R(X_7)T_7}}$$

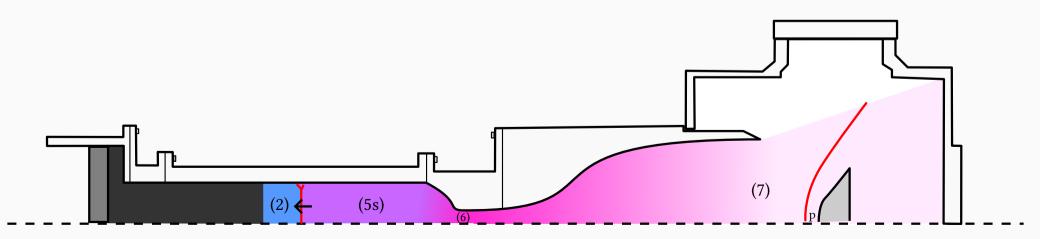
$$p_p = \text{normalshock}(M_7, p_7, T_7)$$

$$\frac{p_p(p_7)}{p_{5s}} - 7.01 \times 10^{-3} = 0$$



Step 6: Isentropic Expansion with Known Pitot/Stag Ratio

	p (kPa)	T (K)	v(m/s)	NOX %	O %
State 1	194	300	0	0	0
State 2	9712	2338	349	1.75	0.15
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State 5s	45,000	3768	0	8.9	0.9
State 6	24,531	3391	1122	6.8	0.7
State 7	4.956	466.8	3005	0	0



Alternate Step 6: Quasi-1D Space Marching with NENZF1d

NENZF1d is a program for fast Reflected Shock Tunnel Analysis:

- Includes thermochemical nonequilibrium in the expanding part of the nozzle
- Solves in seconds or less using a 1D space marching approach
- Accuracy comparable to CFD in a good nozzle

See Peter Jacobs' 2020 CfH Seminar: [6]

Calculation of Test Flow Conditions for Reflected-Shock Tunnels

<u>Peter Jacobs</u>, Wilson Chan, Tamara Sopek, Fabian Zander, Kyle Damm, Nick Gibbons, <u>Rowan Gollan</u>

The University of Queensland (at one time or another)

03 Dec 2020

Link:



NENZF1d uses the state-to-state equilibrium up to the nozzle throat

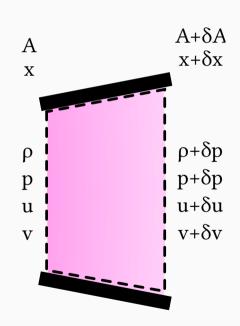
- From there, choose a timestep and march in small increments along the nozzle
- Each increment has a quasi-1D control volume

$$0 = \rho A \delta v + v A \delta \rho + \rho v \delta A$$

$$0 = \rho v \delta v + \delta p$$

$$0 = v E A \delta \rho + (\rho E + p) A \delta v + \rho v A \delta e + (\rho E + p) v \delta A$$

Where: $E = e + \frac{1}{2}v^2$ and $\delta E = \delta e + v\delta v$



These 3 equations are linear in the 4 increments δ :

- Add in the perfect gas equation of state for another equation
- We can solve a linear system for each small control volume

$$\begin{pmatrix} vA & \rho A & 0 & 0 \\ 0\rho v & 1 & 0 \\ vEA & \rho(E+p)A & 0 & \rho vA \\ RT & 0 & -1 & \frac{\rho R}{c_v} \end{pmatrix} \cdot \begin{pmatrix} \delta \rho \\ \delta v \\ \delta p \\ \delta e \end{pmatrix} = \begin{pmatrix} -\rho v \delta A \\ 0 \\ -v(\rho E+p)\delta A \\ 0 \end{pmatrix}$$

But wait! Aren't we trying to include thermochemical nonequilibrium?

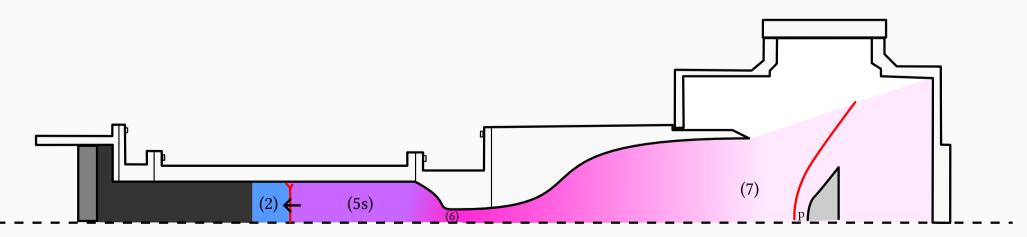
- Run an adiabatic-fixed mass reactor for a short amount of time dt
- Split the pressure increment into $\delta p = \delta p_{\rm chem} + \delta p_{\rm gas}$
- Tv and chemical composition changes are loosely coupled into the marching

$$\begin{pmatrix} vA & \rho A & 0 & 0 \\ 0\rho v & 1 & 0 \\ vEA & \rho(E+p)A & 0 & \rho vA \\ RT & 0 & -1 & \frac{\rho R}{c_v} \end{pmatrix} \cdot \begin{pmatrix} \delta \rho \\ \delta v \\ \delta p_{\rm gas} \\ \delta e \end{pmatrix} = \begin{pmatrix} -\rho v \delta A \\ -\delta p_{\rm chem} \\ -v(\rho E+p)\delta A \\ 0 \end{pmatrix}$$

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State 7:	p (kPa)	T (K)	v (m/s)	NOX %	O %	
ESTCN	4.956	466.8	3005	0	0	
NENZF1d	4.65	426.5	2955	6	4e-11	
error	6.6%	9.5%	1.7%	100%	100%	



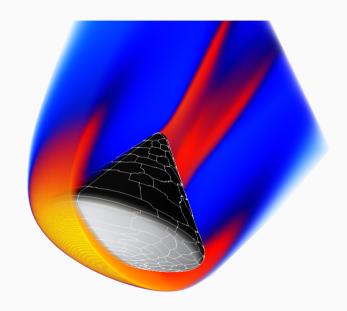
Final Alternate Step 6: 2D Axisymmetric Simulation using Eilmer

Eilmer is our general purpose compressible flow solver:

- Free and open-source
- Structured and Unstructured grids in 2D/3D
- Very capable nonequilibrium thermochemistry models
- Extensively validated against decades of experiments
- Scales on thousands of cores for LES/DNS

Link to CPC Paper: [7]





Apollo capsule at 18.6° angle of attack

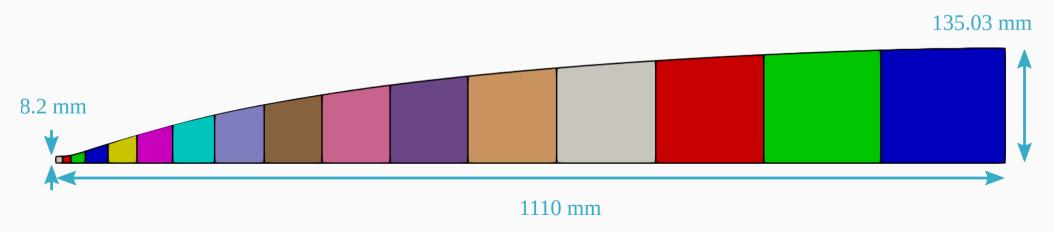
Final Alternate Step 6: 2D Axisymmetric Simulation using Eilmer

Shot 11760 used T4's Mach 8 Nozzle:

- There's a demo simulation of this in the Eilmer examples
- Let's try it!

Simulation Details:

Solver Mode	Gas Model	Turbulence	Grid	n Blocks
Steady Axi-2D	6sp Air 1T	Spalart-Allmaras	191x71	16



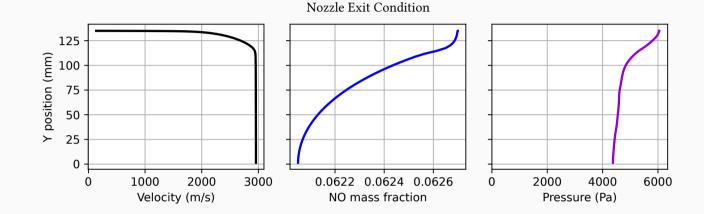
Another Alternate Step 6: 2D Axisymmetric Simulation using Eilmer

Runtime Details:

• Sim Time: 1992 seconds

• CPU: AMD PRO 3955WX x16

• Termination GRR: 1e-12





Final Comparison

We can cut out the core flow and 1Dify it to compare to NENZF1d

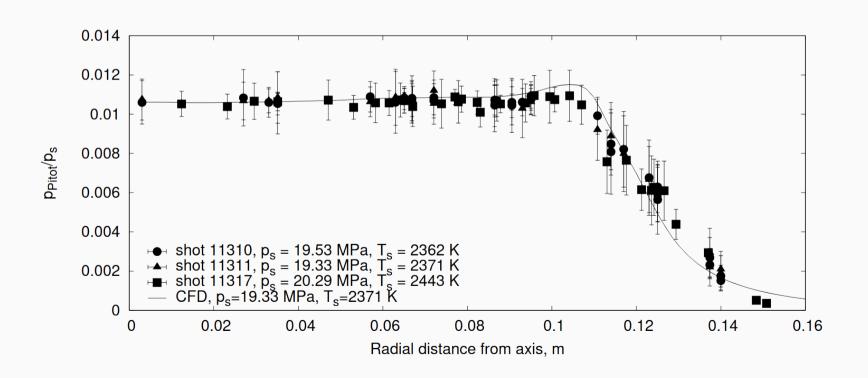
- Matches pretty nicely
- Disclaimer: I did use the predicted pitot/stag from the CFD

State 7:	p (kPa)	T (K)	v (m/s)	NOX %	O %
Eilmer	4.67	427.0	2955.0	6.21	4.27e-11
NENZF1d error	4.65 0.4%	426.5 0.1%	2955.4 0.0%	6.19 0.3%	4.24e-11 0.7%
ESTCN	4.96	466.8	3005	0	0
error	6.1%	9.3%	1.7%	100%	100%

Does it match experiments?

Some testing of the nozzle CFD by Wilson Chan and PJ [3] shows good agreement:

• Pitot rake measurements have pretty large error bars

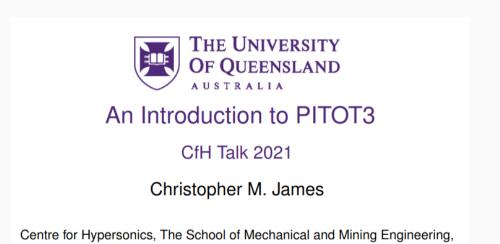


One Last Thing: PITOT3

PITOT is a more flexible state-to-state calculator written and maintained by Dr. Chris James:

- Python code with composable class structure
- Shock Tubes, Expansion Tubes, Diaphragms and Pistons
- Very useful for developing new conditions and other off-design behaviour

See Chris's CfH talk on the website: [8]

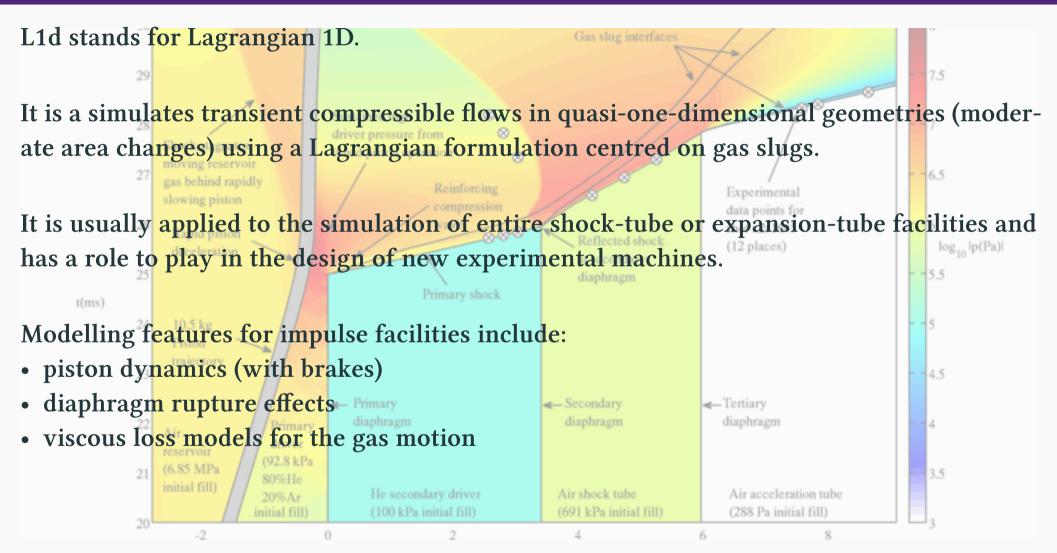


The University of Queensland, Brisbane, QLD, 4072, Australia

PDF Link:



Overview of L1d



L1d: input file demo

```
# exptube.py
config.title = 'Expansion-tube demo, 2020-05-20'
my gm = add gas model('ideal-air-gas-model.lua')
# Define the tube wall.
add break point(0.0, 0.02)
add break point(3.0, 0.02)
# Create the gas-path.
left wall = VelocityEnd(x0=0.0, vel=0.0)
driver gas = GasSlug(p=1.0e6, vel=0.0, T=3000.0, gmodel id=my gm, ncells=200)
interface = GasInterface(x0=0.5)
driven gas = GasSlug(p=5.0e3, vel=0.0, T=300.0, gmodel id=my gm, ncells=100)
dia = Diaphragm(x0=1.0, p burst=10.0e3)
accel gas = GasSlug(p=100.0, vel=0.0, T=300.0, gmodel id=my gm, ncells=300)
free end = FreeEnd(x\theta=2.5)
assemble gas path(left wall, driver gas, interface, driven gas,
                  dia, accel gas, free end)
# Set some time-stepping parameters
config.dt init = 1.0e-8
config.max time = 1.0e-3
config.max step = 9000
add dt plot(0.0, 10.0e-6, 1.0e-6)
add history loc(0.90)
add history loc(2.45)
```

Eilmer: a brief history

- cns4u began life in 1990 (Peter Jacobs, ICASE @ NASA Langley)
- mb_cns started in mid 1990s (Peter Jacobs + grad students @ UQ)
- mbcns2 in early 2000s in C++, generalised thermochemistry modelling
- elmer/elmer2 in early 2000s, 3D code in C with Python
- merge mbcns2 and elmer2 → Eilmer v3 in Nov 2008, C++ core
- Eilmer v4 written in D programming language, began in 2014
- 2024: (soft) release of Eilmer v5

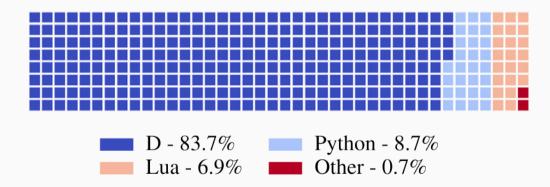
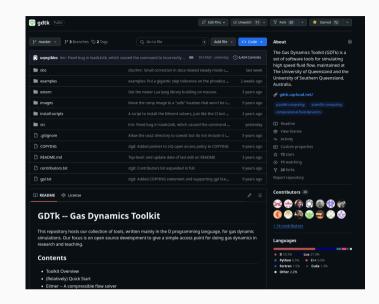


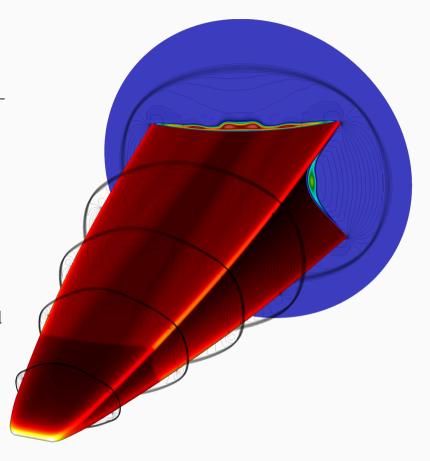
Fig. 4. Division of languages within Eilmer as of April 2022.

source: Gibbons et al. (2023) CPC, 282:108551 [7]



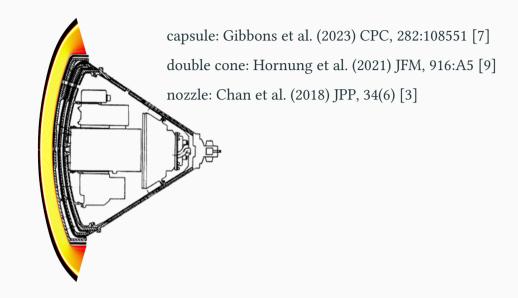
Eilmer: features and capabilities

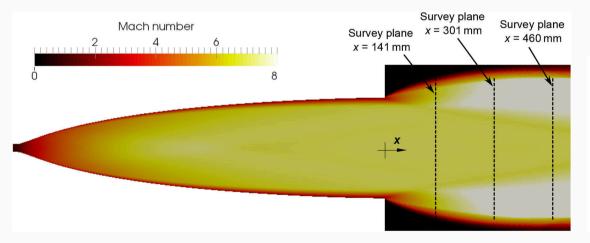
- 2D/3D compressible flow simulation (on body-fitted grids)
- cell-centred finite volume
- 2nd-order with shock-capturing (routine); 4th-order for specialist work
- Gas models include: ideal, thermally perfect, multi-temperature and statespecific
- Kinetics: finite-rate chemistry and thermal nonequilibrium modelling
- Inviscid, laminar, turbulent flows
- Solid domains with conjugate heat transfer
- User-controlled moving grid capability
- Boundary shock-fitting method for blunt-body shock layers
- Transient, time-accurate updates with Runge-Kutta family integrators
- Steady-state accelerator using Newton-Krylov method
- User-defined customisations for boundary conditions, source terms, pre- and post-processing
- Parallel computations using shared memory or distributed memory (MPI)
- Native grid generation and 3rd-party import capability
- Unstructured mesh partitioning via Metis
- Adjoint solver for efficient sensitivities evaluation

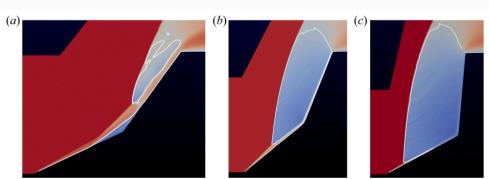


Eilmer: what it's used for

- Experiment support
- Flow physics investigation
- Flow path analysis, design and optimisation







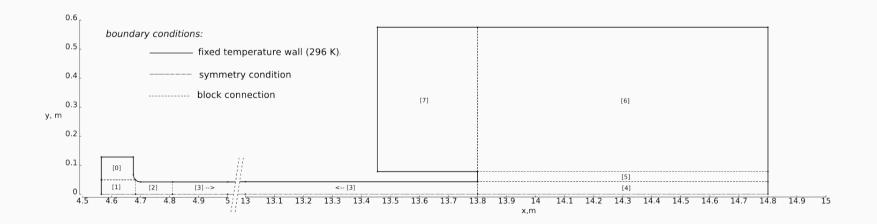
Eilmer for the simulation of impulse facilities

Tech specs:

- solves compressible Navier-Stokes equations in axially-symmetric geometries
- multi-block structured grids
- finite-volume; second-order in space with shock-capturing
- low-order Runge-Kutta family timesteppers for transient simulations
- Newton-Krylov accelerator for steady-state simulations

Features for impulse facility simulation:

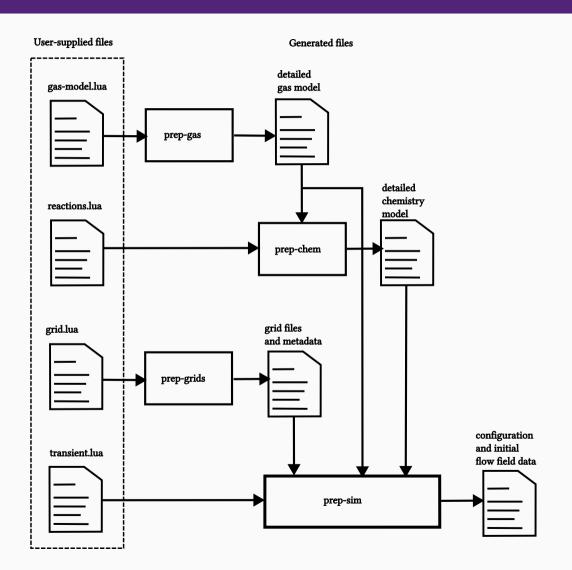
- adaptive flux calculators (for numerical stability near shocks)
- profile-type boundary conditions (for staging or hybrid L1d/eilmer sims)
- user-defined functions to add modelling behaviour, such as diaphragm rupture



Eilmer workflow

- 1. pre-processing
- 2. running a simulation
- 3. post-processing

```
$ lmr prep-gas
$ lmr prep-grid
$ lmr prep-sim
$ lmr snapshot2vtk --all
$ lmr help
```



Scenario: simulation of a T4 experiment

Supersonic turbulent flow over a flat plate

gdtk/examples/lmr/2D/turbulent-flat-plate

Nick N. Gibbons 2024-02-26

This example is a turbulent, supersonic flow over a flat plate at Mach 6.5, from Ye and Morgan (1994). In T4, the boundary layer at this condition is actually transitional, though here it is treated as fully turbulent from the leading edge. Both structured and unstructured variants are available, and the one equation "Edwards" variant of the Spalart-Allmaras turbulence model is used.

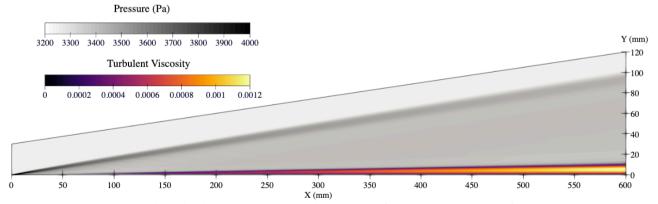


Figure 1. Pressure and turbulent viscosity color maps for the Mach 6.5 flat plate.

ON THIS PAGE

Supersonic flow over a convex corner

Supersonic flow over a wedge

Supersonic flow through a Busemann diffuser

Supersonic turbulent flow over a flat plate

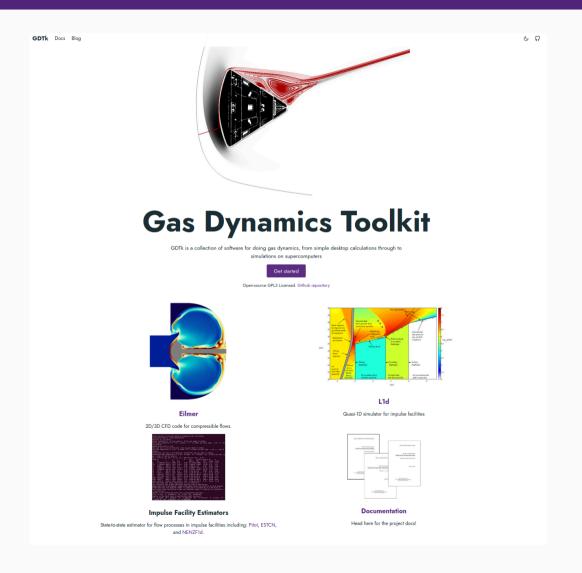
Steepening Wave Problem in 1D

Reacting premixed hydrogen over a 15 degree ramp

Tightly-coupled conjugate heat transfer over a hollow cylinder

Verification via manufactured solutions (in 2D)

Where to find out more



https://gdtk.uqcloud.net



Thanks!

The GDTk Team

Peter Jacobs, Kyle Damm, Reece Otto and the team of PhD students in the CFD group

Peter Jacobs

a large number of the tools presented today were initiated, developed, documented and maintained under his custodianship for over 35+ years (and continues today)

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